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Key Points:

- We successfully discriminate underground nuclear explosions with a Convolutional Neural network (CNN) trained on P-wave seismograms
- Robust global seismic event discrimination is possible with machine learning trained on regional and teleseismic data
- A CNN trained with historical nuclear explosion data can be applied with high accuracy to other regions, like the six Democratic People's Republic of Korea's test explosions

Supporting Information:

Supporting Information may be found in the online version of this article.

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Global Nuclear Explosion Discrimination Using a Convolutional Neural Network

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Abstract Using P-wave seismograms, we trained a seismic source classifier using a Convolutional Neural Network. We trained for three classes: earthquake P-wave, underground nuclear explosion (UNE) P-wave, and noise. With the current absence of nuclear testing by countries that have signed the Comprehensive Test Ban Treaty, high quality seismic data from UNEs is limited. Even with limited training data, our model can accurately characterize most events recorded at regional and teleseismic distances, finding over 95% signals in the validation set. We applied the model on holdout datasets of the North Korean test explosions to evaluate the performance on unique region and station-source pairs, with promising results. Additionally, we tested on the Source Physics Experiment events to investigate the potential for chemical explosions to act as a surrogate for nuclear explosions. We anticipate that machine-learning models like our classifier system can have broad application for other seismic signals including volcanic and non-volcanic tremor, anomalous earthquakes, ice-quakes or landslide-quakes.

Plain Language Summary We train a global seismic event classifier using machine learning on underground nuclear test explosion seismic data. Our classifier model can successfully discriminate (with over 95% accuracy) between underground nuclear explosion, earthquake, and noise signals from stations both regionally and far-field. Since this model was trained on a relatively small data set (for machine learning applications) we expect that similar methods can be applied to event or discrimination of other unique seismic sources like those from volcanoes, landslides, or glaciers.

1. Introduction

Nuclear weapons can have disastrous effects on human life, ecological environments, and public health; ramifications that can last for generations (Wu et al., 2020). According to the 2020 Global Nuclear Power Report (Yearbook, 2021) the number of nuclear weapons is generally reduced in 2020 but states with nuclear weapons continue to modernize nuclear arsenals (Yearbook, 2021). Robust global underground nuclear explosion (UNE) detection is essential for international regulatory bodies such as the Comprehensive Nuclear Test Ban Treaty Organization (CTBTO) and the Air Force Technical Applications Center (AFTAC) to monitor the near-worldwide cessation of nuclear explosive testing and eventually to verify the compliance of the Comprehensive Nuclear-Test-Ban Treaty (CTBT). Although the CTBTO uses a variety of data including continuous seismic, acoustic, hydro-acoustic signals, and radionuclide data, seismic methods have proved to be the most robust and rapid for the purpose of detecting, locating and discriminating UNEs from natural earthquakes and other near surface seismic signals (Maceira et al., 2017). Improved and continued development of underground explosion detection using seismic methods is imperative given that UNE testing is the most likely scenario for all future testing as it allows for control of radioactive explosive products (Maceira et al., 2017).

Existing methods for seismic detection and discrimination include beamforming, template matching, waveform autocorrelation, ratio of body to surface wave magnitudes, and P to S wave amplitude ratio calculations (Bowers & Selby, 2009; Maceira et al., 2017; Schaff et al., 2018; Tibi, 2021; Walter et al., 2018). Although these tools are robust for large yield (>0.5 kt) UNE monitoring (Koper, 2020; Maceira et al., 2017), the ever increasing amounts of seismic data, and lower detection thresholds drives the need for rapid and automated single-station detection algorithms.

Machine learning (ML) methods are widely spreading as a tool in seismology and real-time monitoring (Kong et al., 2019; Yeck et al., 2020) with encouraging potential. ML methods can allow generalizable models that can identify events outside of those used in initial training. This is essential, especially for nuclear explosion



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monitoring where nuclear weapon test explosions are rare after almost all the world's countries signed the CTBT, meaning that all current and future monitoring research and development is dependent on historical nuclear explosion data, with the exception of the Democratic People's Republic of Korea's (DPRK) tests.

The first applications of ML in seismology focused on discriminating the amplitude spectra of seismic waveforms of natural earthquakes, and nuclear and chemical explosions (Dowla et al., 1990; Dysart & Pulli, 1990; S Ren et al., 2020). ML has successfully been applied to discriminate between natural earthquakes and other types of seismic events (UNE's, underwater explosions, volcano-tectonic events) at local or regional distances (Romeo, 1994). These earlier studies typically use limited training labels (e.g., on the order of a few tens or hundreds) and Artificial Neural Networks (ANNs) with shallow fully-connected feed-forward neural networks € and simple recurrent networks (Del Pezzo et al., 2003; Dowla et al., 1990). These networks tend to limit performances (e.g., up to 90% of classification accuracy), limit spatial application, and can be computationally intensive for standard CPU-based computations. More recent developments in deep learning (LeCun et al., 2015; Rouet-Leduc et al., 2017) opened doors for scientists in many fields to be able to utilize historical and relatively small datasets for classifying and discriminating seismic event types or phase determinations (Bergen et al., 2019; a Kong et al., 2019; Nakano et al., 2019) with encouraging results.

Evolved from traditional ML techniques (G. E. Hinton et al., 2006), deep Convolutional Neural Networks 5 (CNNs) have been shown to be highly successful in both image (Krizhevsky et al., 2012) and speech (G. Hinton 5 et al., 2012) processing. In the past few years, seismologists started applying CNNs on seismic waveform data for phase determinations and associations (W. Zhu & Beroza, 2019; Ross et al., 2018, 2019; L. Zhu et al., 2019). event detection and discrimination (Mousavi & Beroza, 2019; Mousavi et al., 2019; Nakano et al., 2019) and source location (Mousavi & Beroza, 2019; Perol et al., 2018; Zhang et al., 2020), and magnitude determination (Mousavi & Beroza, 2020). Other machine learning methods such as Support Vector Machines (SVM). random forests, self-organizing maps, and naive bayes classification have also been used for natural earthquake and explosion discrimination (Pu et al., 2019; Sick et al., 2015; Kim et al., 2020; L. Dong et al., 2014). Studies have found improved recognition ability with CNNs over SVMs for detecting nuclear and chemical explosions with infrasound data. CNNs have been used successfully for non-nuclear explosion and earthquake discrimination in numerous studies, however always in a regional or local setting and not always on the seismic wave-\$ forms (Tian et al., 2022; L.-j. Dong et al., 2020; L. Linville et al., 2019; Trani et al., 2022; Huang et al., 2018; Song et al., 2020). Mousavi et al. (2019)'s earthquake detector "CRED" didn't detect more events than conven-Q tional template matching when applied to a region outside of its training, it did perform faster without the need region-specific waveform templates, which highlights the computational efficiency of CNN's and potential for use in data-limited regions. Generalized Global ML models have been successfully applied to real-time magnitude estimation (Chakraborty et al., 2021; Mousavi & Beroza, 2020) and regional focal mechanism predictions (Kuang et al., 2021), as well as for global operational processing systems at monitoring institutions like the USGS NEIC (Yeck et al., 2020). Both the ML architecture and training data choice are important for developing a robust model. Inconsistency of neural networks for seismic phase prediction are strongly influenced by the training data, \overline{z} and biases there-within that influence a model's generalizability and performance (Park et al., 2023).

With the increasing availability of seismic data recently (up to ten of thousands sensors recording in near real time), it is virtually impossible to manually flag suspicious events (e.g., conventional or nuclear explosions) for $\overline{\mathbb{Q}}$ further analysis. Barama et al. (2022) compiled the Georgia Tech Underground Nuclear Explosions (GTUNE) data set which is a comprehensive seismic waveform and event catalog from a wide range of sources for declassified underground nuclear explosions. With this, we explore the utility of older and lower quality historical data from UNEs in combination with high quality data from the more recent events for developing more robust ML-based global UNE detectors. Here we show that this data set can be used to train a CNN model to automatically discriminate seismic waves generated by earthquakes and nuclear explosions.

The labels for the three training classes of: earthquake P-waves, UNE P-waves and noise are sourced from Barama et al. (2022), including global seismic data stored at the Incorporated Research Institutions in Seismology (IRIS) and Japanese national waveforms from their National Research Institute for Earth Science and Disaster Resilience (NIED), and other networks. The NIED Hi-Net array of data are particularly useful for dense observations of the recent DPRK nuclear tests at local to regional distances. The UNE data include 600 underground nuclear tests

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from the year 1961–2017 (Figure S1 in Supporting Information S1). Earthquakes used range in magnitude from 4.5 to 6.5 (comparable wave amplitude to used nuclear tests), are shallower than 50 km, and recorded at stations less than 90° away. Figure S1 in Supporting Information S1 shows the distribution of UNEs and stations. Since → most historical data was recorded on single channel seismographs, we use only vertical component waveforms for training. L. Linville et al. (2019) showed successful discrimination between surface mine explosions and seismic events at local distances and found that although 3-component data made the CNN predictions more accurate, it was not required for prediction. The training labels are formatted in 20 s windows with the earthquake and UNE P-arrivals fixed at 5 s, which means we are training on 15 s of earthquake and UNE signal. We choose ☑ this window length in order to capture the more impulsive nature of the explosion waveforms when compared to earthquakes recorded at teleseismic distances. Window lengths of 30 and 60 s and windows with random. P-arrival positioning were also tested but we found that waveform duration after the P-wave does not significantly affect the final accuracy. The 20 s windows with fixed P-arrival resulted in the best performing model, but additionally enabled us to have smaller training data, a shallower CNN thus faster training.

A data processing pipeline was created that ingests raw seismic signals and produced a 3-class probability (earthquake, UNE, and noise). We did not remove the instrument response, because such information was not readily available for many historic seismic stations. All methods and pipelines are organized in a Python library we call PyWave. The pipeline was designed to produce a consistent data structure regardless of the recording stations' characteristics to create a user-friendly system, and speed-up processing time. Pre-processing functions included o are for demeaning, resampling, applying a cosine envelope function and a four-corner bandpass filter. Addition-≤ ally we developed and integrated a method into the PyWave library that measures the energy (the sum of the square of the amplitudes) of pre-event noise and event signal, and calculates the signal-to-noise ratio (SNR). This \(\frac{9}{2} \) energy filter method was used to further refine the data set by excluding those waveforms with a very low SNR.

The windowed data is then centered by subtracting the windowed mean value from the signal vector. The resulting time series is then re-sampled to 20 samples per second (sps) using a Fourier method to produce consistent results between stations with different sampling rates. Any signals sampled at greater than 20 sps are down-sampled, while signals sampled at less than 20 sps are discarded. The waveform is demeaned and then a cosine envelope function is applied at the beginning and end 4% of the re-sampled window. This minimizes edge effects that may otherwise be created in subsequent processing. Because data cover a wide range of distances, a number of filter ranges were tested that could accommodate valuable information for all data. We found we retained the most data Q of energy filter threshold greater than 5 as well as model performance with data filtered between 1 and 5 Hz using a digital Butterworth filter.

Maceira et al. (2017) showed that seismo-acoustic wave amplitude—yield relationship can vary and depends on many factors such as emplacement geologic conditions and depth. To address such amplitude variations, we applied a signal normalization function to the data before feeding them into the CNN classifier. Signal normalization scales all signals so they are roughly the same order of magnitude, ranging from -1 to 1, while retaining all an algorithm generally considers waveforms with a strong feature as more important and focus on these features and during the training process. The normalization process is used to prevent this deleterious behavior.

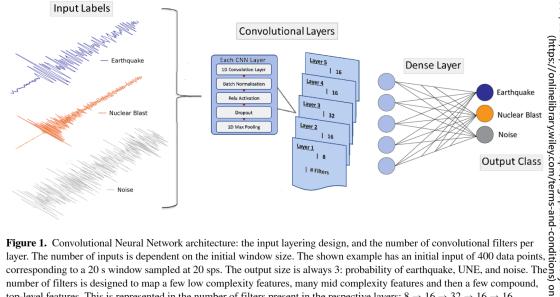
3. CNN Model Architecture and Training

The deep learning classifier we used is composed of many fully-connected one-dimensional convolutional layers bundles, following an architecture used by L. Zhu et al. (2019). In total there are 6 CNN layers and conditions of the control of the salient features. When training an algorithm, feature importance can be associated with feature amplitude. Thus

bundles, following an architecture used by L. Zhu et al. (2019). In total there are 6 CNN layers and one dense output layer as shown in Figure 1. The number of inputs is dependent on the initial window size, which has an initial input of 400 data points, corresponding to a 20 s window sampled at 20 sps. The output size is always 3: probabilities of earthquake, UNE, and noise, respectively. The number of convolution filters in each layer is designed to map a few low complexity features, many mid complexity features and then a few compound, top-level features.

Each layer in the CNN bundle is composed of multiple sub-layers as shown in Figure 1. These layers are a 1D convolution, batch normalization, activation, dropout, and a 1D max pooling layer. The batch normalization layer scales the inputs for better generalization and also improves computation speed. The activation layer applies the "ReLU" (rectified linear activation unit) function to each input. The dropout layer randomly re-initializes a

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number of filters is designed to map a few low complexity features, many mid complexity features and then a few compound, top-level features. This is represented in the number of filters present in the respective layers: $8 \to 16 \to 32 \to 16 \to 16$. number of filters is designed to map a few low complexity features, many mid complexity features and then a few compound,

combines all kerneled layers back into one layer. Pooling operations allow the model to learn multiple templates at different resolutions by changing the resolution of the filtered input waveform (Ren et al., 2020). Lastly, a softmax layer is included, so that the output predicted probability distribution total sums up to 1.

The CNN classifier was trained and tested on a subset of the cumulative data set discussed above. Interestingly, the best performing models were those with an energy threshold of ~5; higher signal-to-noise ration. (SNR) thresholds would substantially reduce the training data used. After applying the energy filter, the nuclear data set retained 14,302 observations, 44.7% of the original data set. One thousand traces of this data set were. randomly removed as a holdout set for final testing for nuclear, earthquake and noise labels. An additional 10% per was randomly removed from the remaining data set for training and testing. Since it is important to keep and balanced training and testing data set to equally represented classes and give similar internal weighting to results (Megahed et al., 2021), the earthquake and noise datasets were randomly reduced to match the nuclear data set

(Megahed et al., 2021), the earthquake and noise datasets were randomly reduced to match the nuclear data set a training and test size. In Table S1 in Supporting Information S1 and Table S2 detail number of waveforms used in go for training and testing and the CNN classifier structure as adjusted for a 20 s window sampled at 20 sps (input size of 400) with 1 channel vertical component data, respectively.

4. Results and Testing Model Performance

Using the training and test data presented in Table S1 in Supporting Information S1, a single-channel CNN model place was trained on the vertical component, pre-processed seismograms. After tuning the hyper-parameters, a dropout of 8% and a batch size of 500 were selected. We trained the model for 100 epochs. The trained CNN was used of 8% and a batch size of 500 were selected. We trained the model for 100 epochs. The trained CNN was used of 8% and a batch size of 500 were selected. We trained the model for 100 epochs. The trained CNN was used of 8% and a batch size of 500 were selected. We trained the model for 100 epochs. The trained CNN was used of 8% and a batch size of 500 were selected. We trained the model for 100 epochs. The trained CNN was used of 8% and a batch size of 500 were selected. We trained the model for 100 epochs. The trained CNN was used of 8% accuracy of Figure 2). The holdout datasets include earthquakes, noise, UNE, source physics experiment (SPE) chemical of 8% accuracy of 95% accuracy. The selective of 8% accuracy of 8% accuracy of 95% accuracy. The selective of 95% accuracy of 95% acc

It is important to have confidence that current empirical and limited test-site based methods will work in all regions of the world, even in under-tested emplacement conditions. This drives physics-based simulation and

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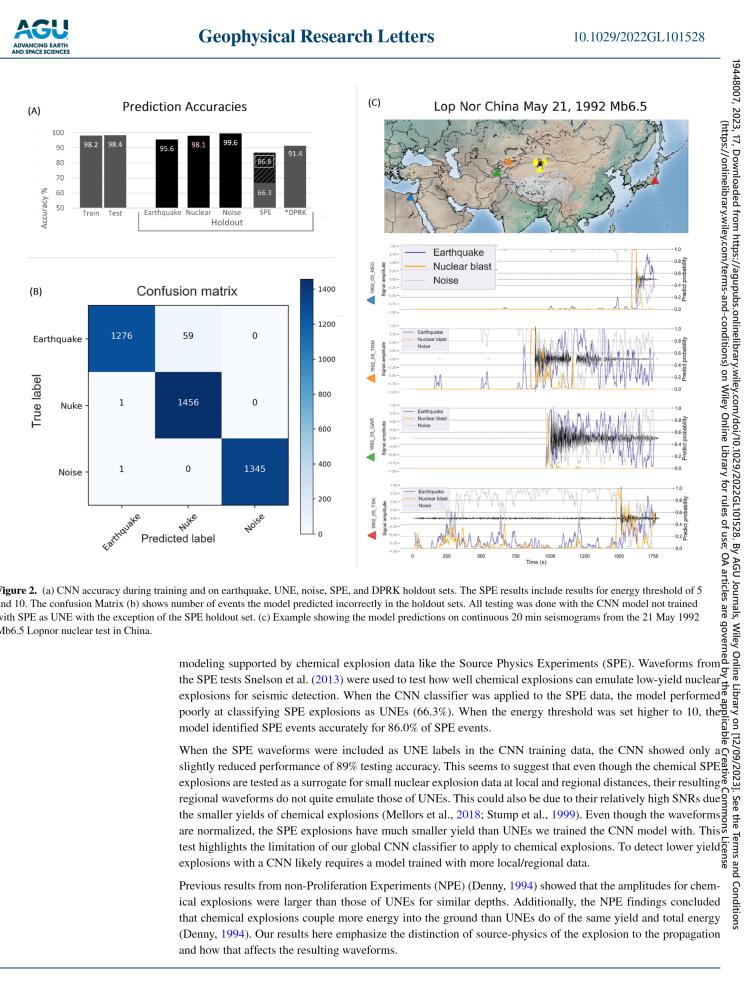
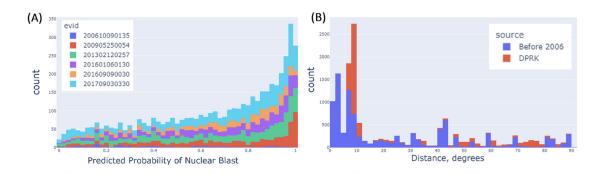
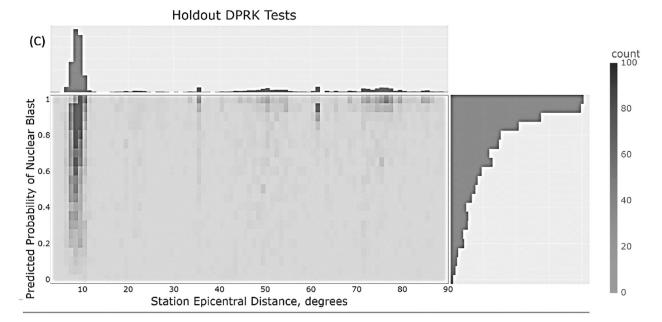


Figure 2. (a) CNN accuracy during training and on earthquake, UNE, noise, SPE, and DPRK holdout sets. The SPE results include results for energy threshold of 5 and 10. The confusion Matrix (b) shows number of events the model predicted incorrectly in the holdout sets. All testing was done with the CNN model not trained with SPE as UNE with the exception of the SPE holdout set. (c) Example showing the model predictions on continuous 20 min seismograms from the 21 May 1992 Mb6.5 Lopnor nuclear test in China.

(Denny, 1994). Our results here emphasize the distinction of source-physics of the explosion to the propagation and how that affects the resulting waveforms.

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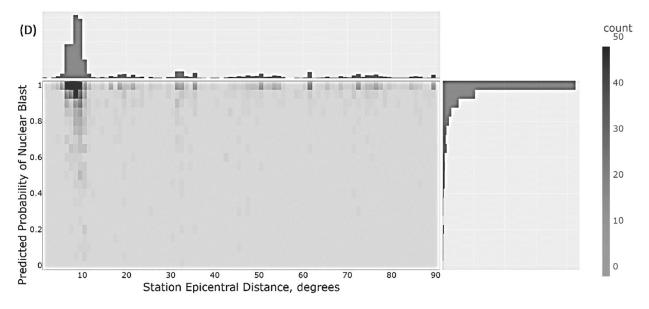


Figure 3. Testing on the DPRK holdout data set model and the global data set (a) Predicted probabilities of UNE for each of the 6 DPRK nuclear test explosions (events 2006 to 2017, with Mb 4.3 to 6.3). (b) Count of label waveform station distance in training (blue) and DPRK (red) datasets. (c) Distribution of predicted UNE probability and station distance is shown for the DPRK holdout model and (d) the global model. Histogram distribution of waveform station distance and model prediction probability are top and bottom bar graphs.

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4.2. Holdout Testing on the North Korea Nuclear Test Explosions

Up to now we randomly split the data set into training, holdout, and test sets. However because nuclear waveforms from any specific source-receiver pair are likely to be highly similar (e.g., the 6 DPRK nuclear tests) (Lay, 2021; Voytan et al., 2019), it is possible that our algorithm has already seen the waveform from that particular source-receiver path during the training process, resulting in a high success rate (i.e., data leakage). § This likely occurs because the algorithm is learning the Green's function that represents the path-effect rather than training on the fundamental differences in the waveform and source characteristics. To test the model's $\overline{\Sigma}$ performance on unique source-receiver pairs as well as the usefulness of the historical seismograms, we trained an additional model excluding all 6 DPRK tests. Figure S1 in Supporting Information S1 shows the distribution ₹ of stations used for DPRK events for testing and global historical data. Following the same procedure for data preparation and model training as using the full data set, the model accuracy for nuclear, noise, and earthquake holdout sets was 90.1%, 99.7%, and 95.8%, respectively. When applying the model to the 4871 DPRK traces, the model prediction accuracy for UNE is 91.4%. Figure 3 displays the details of the difference in training data for an object the global model and the DPRK holdout data, as well as difference in model performance with station distance. Our results suggest that our CNN model is capable of identifying UNEs from a region excluded from the training odd data set as well as a range of magnitudes from Mb 4.3 to 6.3 (Figure 3a). Although the historical waveforms are from more diverse set of stations and have source-receiver pairs all over the world, the model does generalize to be applicable to other regions.

4.3. Application to Continuous Data Sets

The results so far have shown that our CNN classifier was effective on a curated data set. Next we perform an additional test for its performance on continuous waveform data where we apply a moving average to a three-class library wiley. Online the predictor (Figure 2). The algorithm class prediction is assigned to the class with the highest probability. Noterly 2020 that for a three-class algorithm, the highest probability may not be a majority. In the example of the 12 May 1992 to 100 that for a three-class algorithm, the highest probability may not be a majority. In the example of the 12 May 1992 to 100 that for a three-class algorithm tends to predict an earthquake when it is exposed to a limited P-arrival signal. When it is exposed to a limited P-arrival signal. When it is exposed to a limited P-arrival signal. preparation and model training as using the full data set, the model accuracy for nuclear, noise, and earthquake

algorithm tends to predict an earthquake when it is exposed to a limited P-arrival signal. When it is exposed to a larger portion of the signal, it predicts a UNE with much higher confidence. Because the three-class classifier. does not recognize other signals, any nuisance event is necessarily categorized as either an earthquake, nuclear test, or noise.

5. Discussion

Given the modest size of our training set, we have higher prediction variance and more false positives (predicting earthquakes as UNE) than we would expect from a deep-learning model with deeper layers. This is suggested by a the results of L. Zhu et al. (2019) for earthquake phase detection, in which the authors did not have such issues while using a similar approach but with a training set that was an order of magnitude larger than ours. Without substantially more nuclear event waveforms this will remain a limitation of our work, however, event-based training could prove useful to combat these limitations (L. M. Linville, 2022). The issue is still quite small, affecting $\overline{\overline{a}}$ only 2% of the signals. Too, as this method is testing solely on individual waveforms, network-based solutions should quickly correct for most, if not all of these false positives.

In a comparative study, Chen et al. (2018) used a small data set of 72 earthquakes and 101 man-made explosions 6 around Beijing, China to train a CNN to discriminate explosions from earthquakes. Unlike this study, Chen S et al. (2018) trained their CNN on the extracted Mel Frequency Cepstrum Coefficient (MFCC) map, not seismic 3 waveforms, and found an average recognition rate of 95.78%. Though there are limitations, our model result of ₹ holdout accuracy of over 98% for global UNEs is a promising result.

Koper (2020) stressed the importance of lowering the detection threshold of explosions using the International Monitoring System (IMS) global seismic network at local and regional distances. Kong et al. (2022) used local augmented waveforms and P-S ratios from 90 explosions in Northwest United States to train a deep learning model as an explosion-earthquake discriminator with high rates of success. However, their model did not perform well when applied to other regions. Our preliminary tests on the DPRK data already demonstrated that our model successfully generalizes to global (both regional and teleseismic) sources and stations. However, there

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are opportunities to test how to create improved performance of the algorithm such as including synthetic tests or augmented waveforms to improve the diversity and size of the training datasets. Kong et al. (2022) increased their explosion training explosion data from 8,502 to 178,059 traces by using data augmentation. For our case,⊋ data augmenting to create a larger data set would allow us to train station-distance dependent models to test 3 3 performance compared to the global model. Modifying the training method to require unique source-receiver pairs between training and test sets could also improve performance, however since many locations were re-used for nuclear tests, this would exclude a lot of data, and especially high-quality digital data from the recent DPRK events. There remains potential for our current algorithm to be fine-tuned toward specific regions or station distances. Furthermore, developing these algorithms have far-reaching potential beyond automatic nuclear detection as well, and may be adapted to automatic detection of seismic signals associated with deep earthquakes, glacier or ice-quakes, magmatic movements at depth, dangerous slow-source tsunami-generating earthquakes, or \(\frac{Q}{2} \) other features that may rapidly and automatically illuminate a host of geophysical hazards (e.g., initiation phase of seismogenic landslides).

6. Conclusions

In this study, we successfully built a robust global earthquake, UNE, and noise discriminator with available ចឹ limited and balanced data. The prediction accuracy on the class-specific holdout sets were 99.6% for noise, 98.4% for UNE, and 95.6% for earthquake. This work shows promising applications in single-station discrimination earthquakes and UNEs recorded at a global network of stations. Furthermore, our results suggest that ML classifier systems could have broad application for other global and "small data" seismic signals without necessarily or relying on the use of synthetic or augmented data.

Data Availability Statement

Most of the waveforms and metadata used in this work are sourced from the GTUNE repository (Baramage)

et al., 2022), the facilities of EarthScope Consortium and Japan's Data Management Center of the National Research Institute for Earth Science and Disaster Resilience (NIED DMC) Hi-Net array data (National Research Institute for Earth Science and Disaster Resilience, 2019). EarthScope Consortium services are funded through the Seismological Facility for the Advancement of Geoscience (SAGE) Award of the National Science Founda-§ tion under Cooperative Support Agreement EAR-1851048. Python was used for seismic data processing, specifically using the ObsPy package (Beyreuther et al., 2010) and Tensorflow (Abadi et al., 2016) for machine learning. The pre-processing library and CNN model structure *PyWave* is available on Zenodo (https://doi.org/10.5281/\overline{\text{m}} zenodo.7809356).

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